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APPLICATION NO.	FILING DATE	FIRST NAMED INVENTOR	ATTORNEY DOCKET NO.	CONFIRMATION NO.
09/826,715	04/05/2001	Chang-Qing Shu	00-4023	3951
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VERIZON CO	ORPORATE SERVICES	GROUP INC.	BRANT, I	DMITRY
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Please find below and/or attached an Office communication concerning this application or proceeding.

	Application No.	Applicant(s)	
	09/826,715	SHU ET AL.	
Office Action Summary	Examiner	Art Unit	
	Dmitry Brant	2655	
The MAILING DATE of this communication app Period for Reply	ears on the cover sheet with the	correspondence address	
A SHORTENED STATUTORY PERIOD FOR REPLY THE MAILING DATE OF THIS COMMUNICATION.  - Extensions of time may be available under the provisions of 37 CFR 1.13 after SIX (6) MONTHS from the mailing date of this communication.  - If the period for reply specified above is less than thirty (30) days, a reply If NO period for reply is specified above, the maximum statutory period we Failure to reply within the set or extended period for reply will, by statute, Any reply received by the Office later than three months after the mailing earned patent term adjustment. See 37 CFR 1.704(b).	6(a). In no event, however, may a reply be till within the statutory minimum of thirty (30) day ill apply and will expire SIX (6) MONTHS from cause the application to become ABANDONE	mely filed  ys will be considered timely.  the mailing date of this communication.  ED (35 U.S.C. § 133).	
Status	1	•	
1) Responsive to communication(s) filed on 4/05/0	<u>)1</u> .		
2a) This action is <b>FINAL</b> . 2b) ☐ This	action is non-final.		
3) Since this application is in condition for allowan			
closed in accordance with the practice under Ex	k parte Quayle, 1935 C.D. 11, 4	53 O.G. 213.	
Disposition of Claims			
4) Claim(s) 1-32 is/are pending in the application. 4a) Of the above claim(s) is/are withdrawn from consideration.  5) Claim(s) is/are allowed.  6) Claim(s) 1-32 is/are rejected.  7) Claim(s) is/are objected to.  8) Claim(s) are subject to restriction and/or election requirement.			
Application Papers			
9) The specification is objected to by the Examiner.			
10) The drawing(s) filed on is/are: a) acce			
Applicant may not request that any objection to the d	* * * * * * * * * * * * * * * * * * * *	· ·	
Replacement drawing sheet(s) including the correction is required if the drawing(s) is objected to. See 37 CFR 1.121(d).  11) The oath or declaration is objected to by the Examiner. Note the attached Office Action or form PTO-152.			
Priority under 35 U.S.C. § 119			
12) Acknowledgment is made of a claim for foreign p a) All b) Some * c) None of:  1. Certified copies of the priority documents 2. Certified copies of the priority documents 3. Copies of the certified copies of the priorit application from the International Bureau * See the attached detailed Office action for a list of	have been received. have been received in Application y documents have been receiven (PCT Rule 17.2(a)).	on No ed in this National Stage	
Attachment(s)			
1) Notice of References Cited (PTO-892) 2) Notice of Draftsperson's Patent Drawing Review (PTO-948) 3) Information Disclosure Statement(s) (PTO-1449 or PTO/SB/08) Paper No(s)/Mail Date  S. Patent and Trademark Office	4) Interview Summary Paper No(s)/Mail Da 5) Notice of Informal Pa		

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#### **DETAILED ACTION**

## Claim Rejections - 35 USC § 102

1. The following is a quotation of the appropriate paragraphs of 35 U.S.C. 102 that form the basis for the rejections under this section made in this Office action:

A person shall be entitled to a patent unless -

(b) the invention was patented or described in a printed publication in this or a foreign country or in public use or on sale in this country, more than one year prior to the date of application for patent in the United States.

2. Claims 1 and 6 are rejected under 35 U.S.C. 102(b) as being anticipated by Sharma et al (5,862,519)

The U.S. patent of Sharma et al. teach computer-based apparatus (system) and hence the methods and computer code necessary to implement this system are inevitably part of their teachings.

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Limitati	ons	Sharma et al.
Receiving frames	of acoustic data	Computing Spectral Variation Function (SVF),
Determining ceps	tral coefficients for	which is based on the Euclidian norm of delta
each of the receiv	red frames of acoustic	cepstral coefficients of each individual frame (Col.
data		6, lines 32-38). This process inherently
		presupposes fragmentation of acoustic data into
		frames and computing cepstral coefficients for
		each frame.
Segmenting the r	eceived frames of	Segmentation is performed based on the values of
acoustic data base	ed on the determined	Kmax and Kmin (elems. 20, 22, FIG. 1 and Col.
cepstral coefficie	nts.	7, lines 23-28). K max (maximum number of
		segments for each frame ) is computed using SVF
		(Col. 6, line 29-31), which itself is a function of
		cepstral coefficients (Eq. 2). Therefore,
		segmentation of each frame is ultimately
		performed based on the cepstral coefficients.

3. Claims 10 and 12-14, 15, 18-19, 20, 22-25, 28, 29 are rejected under 35 U.S.C. 102(b) as being anticipated by Juang et al. (5,812,972)

The U.S. patent of Juang et al. teach computer-based apparatus (system) and hence the methods and computer code necessary to implement this system are inevitably part of their teachings.

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Claim#	Limitations	Juang et al.
10,15	Receiving frames of acoustic data	(Elem. 315, FIG. 3), which corresponds to a frame of
		acoustic data.
	Determining segmentation information	
	corresponding to the received frames of	(Elem. 330, FIG. 3)
	acoustic data	
	Determining at least one weighting parameter	(Elem. 360, FIG. 3), where W(i) is a weighting
	based on the determined segmentation	factor based on the confidence level of the current
	information	segmentation vector. (Col. 8, lines 55-59)
	Recognizing patterns in the received frames of	(Elem. 355, FIG. 3)
	acoustic data using the at least one weighting	
	parameter	
12,17	Determining, based on the frames of acoustic	(Elem. 327, FIG. 3) uses HMM to determine the next
	data, recognition hypothesis scores using a	likely state (Col. 7, lines 44-48)
	Hidden Markov Model	
13, 14,	Modifying the recognition hypothesis scores	As it can be seen from FIG. 3, readjusted scores are
19	based on the at least one weighting parameter	fed from block 360 back into block 325. Thus the
	and	HMM and corresponding scores are updated using
	the recognizing patterns in the frames of	the weighting factor Wi (elem. 360, FIG. 3) which
	acoustic data further uses the modified	reflects the level of confidence in the current model.
	recognition hypothesis scores	Therefore, the final recognition result (Elem. 355,
		FIG. 3) will incorporate the modification through
		weighting factor W.

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20, 29	Receiving frames of acoustic data	(Elem. 315, FIG. 3), which corresponds to a frame of
		acoustic data.
	Determining first segmentation information	For each sequential frame, modified Observation
	corresponding to the received frames of	vector O''(i), is computed along with segmentation
	acoustic data and second segmentation	vector A(i) (Col. 8, lines 7-17)
	information corresponding to the received	
	frames of acoustic data.	
	Determining at least one weighting parameter	(Elem. 360, FIG. 3), where W(i) is a weighting
	based on the determined second segmentation	factor based on the confidence level of the current
	information	segmentation vector. (Col. 8, lines 55-59)
	Recognizing patterns in the received frames of	(Elem. 355, FIG. 3)
	acoustic data using the at least one weighting	
	parameter.	
22	Comparing the determined first and second	Col. 8, lines 45 - 48
	segmentation information	

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23	The recognizing patterns in the frames of	As it can be seen from FIG. 3, readjusted scores are
	acoustic data is based on the comparison of the	fed from block 360 back into block 325. Thus the
	first and second segmentation information	HMM and corresponding scores are updated using
		the weighting factor Wi (elem. 360, FIG. 3) which
		reflects the level of confidence in the current model.
		Therefore, the final recognition result (Elem. 355,
		FIG. 3) will incorporate the modification through
		weighting factor W which includes comparison of
		O''(i) and A(i)
24	Determining, based on the frames of acoustic	(Elem. 327, FIG. 3) uses HMM to determine the next
	data, recognition hypothesis scores using a	likely state (Col. 7, lines 44-48)
	Hidden Markov Model	
25,28	Modifying the recognition hypothesis scores	As it can be seen from FIG. 3, readjusted scores are
	based on the at least one weighting parameter	fed from block 360 back into block 325. Thus the
	and	HMM and corresponding scores are updated using
	the recognizing patterns in the frames of	the weighting factor Wi (elem. 360, FIG. 3) which
	acoustic data further uses the modified	reflects the level of confidence in the current model.
	recognition hypothesis scores	Therefore, the final recognition result (Elem. 355,
		FIG. 3) will incorporate the modification through
		weighting factor W.

## Claim Rejections - 35 USC § 103

- 3. The following is a quotation of 35 U.S.C. 103(a) which forms the basis for all obviousness rejections set forth in this Office action:
  - (a) A patent may not be obtained though the invention is not identically disclosed or described as set forth in section 102 of this title, if the differences between the subject matter sought to be patented and the prior art are such that the subject matter as a whole would have been obvious at the time the

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invention was made to a person having ordinary skill in the art to which said subject matter pertains. Patentability shall not be negatived by the manner in which the invention was made.

4. Claims 2-5, 7-9, 30, are rejected under 35 U.S.C. 103(a) as being unpatentable over Sharma et al.

The U.S. patent of Sharma et al. teach computer-based apparatus (system) and hence the methods and computer code, such as data structures, necessary to implement this system are inevitably part of their teachings.

As per claims 2-4, Sharma et al. do not disclose determining the number of peaks in cepstral coefficients for each frame and then segmenting the frames based on the comparison of the number of peaks in each of the sequential frames

(Peak N Difference). The applicant discloses that the reason for tracking the variation in the number of peaks is to identify frames having phoneme boundaries, where the number of cepstral coefficient peaks change rapidly [Disclosure, Page. 6, lines 15-16].

Similarly, Sharma et al. applies this principle for computing the maximum number of peaks (Kmax). Sharma et al. discloses Spectral Variation (SVF) function which is computed based on the time variation of cepstral coefficients for each frame. (Col. 6, lines 32-38). To identify segments based on phoneme boundaries, Sharma tracks the peaks in SVF, because SVF exhibits peaks at boundaries where characteristics of speech change rapidly (Col. 6, lines 63-67). SVF tracks the frame-to-frame changes between the corresponding cepstral coefficients within individual frames (See Eq. 2) and thus, changes in the number of peaks would also affect SVF, so that SVF would

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track the frames identified by the applicant's method as having high "Peak\_N\_Difference".

Therefore, it would have been obvious to one of ordinary skill in the art at the time the invention was made to modify Sharma to use the difference in the number of cepstral peaks instead of SVF, because these methods track the same cepstral properties in a similar fashion. Computing the difference in the number of peaks is a variation of SVF, and while not being as exact as SVF, it has the advantage of computational simplicity.

As per claim 5, Sharma et al. discloses <u>receiving frames of acoustic data and computing cepstral coefficients for each frame</u> - Sharma et al. computes Spectral Variation Function (SVF), which is based on the Euclidian norm of delta cepstral coefficients of each individual frame (Col. 6, lines 32-38). This process inherently presupposes fragmentation of acoustic data into frames and computing cepstral coefficients for each frame.

Sharma et al. do not disclose a processing unit that determines the number of peaks in cepstral coefficients for each frame and then segments the frames based on the comparison of the number of peaks in each of the sequential frames

However, Sharma et al.'s Spectral Variation (SVF) function is computed based on the time variation of cepstral coefficients for each frame. (Col. 6, lines 32-38). To identify segments based on phoneme boundaries, Sharma tracks the peaks in SVF, because SVF exhibits peaks at boundaries where characteristics of speech change

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rapidly (Col. 6, lines 63-67). SVF tracks the frame-to-frame changes between the corresponding cepstral coefficients within individual frames (See Eq. 2) and thus, changes in the number of peaks would also affect SVF, so that SVF would track the frames identified by the applicant's method as having high "Peak\_N\_Difference".

Therefore, it would have been obvious to one of ordinary skill in the art at the time the invention was made to modify Sharma et al. to use the difference in the number of cepstral peaks instead of SVF, because these methods track the same cepstral properties in a similar fashion. Computing the difference in the number of peaks is a variation of SVF, and while not being as exact as SVF, it has the advantage of computational simplicity.

5. Claims 11,16, 18, 22, 26-27, are rejected under 35 U.S.C. 103(a) as being unpatentable over Juang et al., in view of Sharma et al.

As per claims 11 and 16, Juang et al. do not disclose "determining cepstral coefficients for the received frames of acoustic data, wherein the determining of the segmentation information is based on the determined cepstral coefficients."

Sharma et al. disclose performing segmentation based on the values of Kmax and Kmin that depend on cepstral coefficients. (elems. 20, 22, FIG. 1 and Col. 7, lines 23-28). Since, K max (maximum number of segments for each frame) is computed using SVF (Col. 6, line 29-31), which itself is a function of cepstral coefficients (Eq. 2),

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the segmentation of each frame is ultimately performed based on the cepstral coefficients.

It would have been obvious to one of ordinary skill in the art at the time the invention was made to modify Juang et al. as taught by Sharma et al. in order to augment the segmentation process of frame data, because the detection of phoneme boundaries using cepstral coefficients would improve the speed and accuracy of the resulting segmentation process.

As per claim 18, Juang et al. discloses the method where readjusting scores are fed from block 360 back into block 325. (FIG.3) Thus the HMM and corresponding scores are updated using the weighting factor Wi (elem. 360, FIG. 3) which reflects the level of confidence in the current model. Therefore, the final recognition result (Elem. 355, FIG. 3) will incorporate the modification through weighting factor W.

As per claim 21, Juang et al. do not disclose "determining cepstral coefficients for the received frames of acoustic data, wherein the determining of the segmentation information is based on the determined cepstral coefficients."

Sharma et al. disclose performing segmentation based on the values of Kmax and Kmin that depend on cepstral coefficients. (elems. 20, 22, FIG. 1 and Col. 7, lines 23-28). Since, K max (maximum number of segments for each frame) is computed using SVF (Col. 6, line 29-31), which itself is a function of cepstral coefficients (Eq. 2),

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the segmentation of each frame is ultimately performed based on the cepstral coefficients.

It would have been obvious to one of ordinary skill in the art at the time the invention was made to modify Juang et al. as taught by Sharma et al. in order to augment the segmentation process of frame data, because the detection of phoneme boundaries using cepstral coefficients would improve the speed and accuracy of the resulting segmentation process.

As per claim 26-27, Juang et al. do not disclose re-ordering the modified recognition hypothesis scores, and further using the re-ordered modified recognition hypothesis scores for the recognizing of the patterns in the frames of acoustic data.

However, it would have been obvious to one of ordinary skill in the art at the time the invention was made that modification of HMM scores (training) (as applied to claim 25) would necessarily involve re-ordering of scores of HMM outcomes.

6. Claims 31,32 are rejected under 35 U.S.C. 103(a) as being obvious over Muroi (4,918,731)

Muroi does not disclose processing unit for generating frame numbers and trainer/HMM decoder.

Muroi discloses:

receiving frames of speech data (12, FIG. 1)

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 the use of end frame numbers to compute duration of the speech pattern (phoneme segment) (Col. 7, lines 10-20). The duration of speech pattern is itself used in the calculations of weights for HMM state transitions (Col. 5, line 50). Therefore, frame numbers are used for calculation of weights for HMM state transitions.

It would have been obvious to one of ordinary skill in the art at the time the invention was made that the system of Muroi necessarily involved a processing unit that generated frame numbers and a trainer/HMM decoder for using the frame numbers to generate weights, since Muroi's system comprises hardware and software, and thus would require modules which would produce the corresponding frames numbers and also recognize patterns using weighted HMM transition probabilities.

### Conclusion

7. The prior art made of record and not relied upon is considered pertinent to applicant's disclosure.

Fanty et al. (6,535,851) teaches speech segmentation based on cepstral coeffecients (6,535,851)

Ruey-Ching et al., "Improvement in Connected Mandarin Digit Recognition by Explicitly Modeling Coarticulatory Information" teaches that the number of peaks in cepstral

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coefficients remains the same across the frames corresponding to the same segments.

(p. 655)

Naylor et al (5,806,034) teach the system for backtracking in HMMs which relies on

frame numbers. (FIG. 7)

Junqua (5,806,030) teaches clustering methods for HMM speech recognizers.

8. Any inquiry concerning this communication or earlier communications from the

examiner should be directed to Dmitry Brant whose telephone number is (703) 305-

8954. The examiner can normally be reached on Mon. - Fri. (8:30am - 5pm).

If attempts to reach the examiner by telephone are unsuccessful, the examiner's

supervisor, Talivaldis Ivars Smits can be reached on (703) 306-3011. The fax phone

number for the organization where this application or proceeding is assigned is (703)

872-9306.

Any inquiry of a general nature or relating to the status of this application or

proceeding should be directed to Tech Center 2600 receptionist whose telephone

number is (703) 305- 4700.

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DORIS H. TO SUPERVISORY PATENT EXAMINER

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